

Conditional expectation and statistics

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Introduction to filtering 2010

Organization/Plan

Organization

- ▶ Four topics
- ▶ Weekly session (Friday)
- ▶ Each topic covered in two or four sessions
- ▶ No sessions in September

Plan

- ▶ Conditional expectation and statistics
- ▶ Discrete time martingales
- ▶ Brownian stochastic calculus
- ▶ Optimal filtering equations

Goals

Learning

- ▶ Sequel to Jonathan's course, "Measure theoretic probability"
- ▶ More compact and applicable language of mathematical probability
- ▶ A closer knowledge of bibliography on probability and statistics

Applications

- ▶ Statistics : point estimation
- ▶ Probability : Martingales
- ▶ Stochastic calculus : Itô integral
- ▶ Filtering : Derivation and general form

Conditional expectation and statistics

20 August

- ▶ Introduction and examples :
 1. Kolmogorov's (measure theoretic) axioms
 2. Three way of interpreting probability?
 3. First example of conditional expectation
 4. Random variables
 5. Expectation
 6. Distribution of a random variable
 7. Independence
- ▶ Inequalities and convergence

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- ▶ Conditional expectation
- ▶ Point estimation

1-Kolmogorov axioms

Kolmogorov, *Foundations of probability*, 1933 : “This task would have been a rather hopeless one before the introduction of Lebesgue’s theories ...”

Probability space : Let $(\Omega, \mathcal{A}, \mathbb{P})$...

- ▶ Ω sample space, probability space : set of possible outcomes
- ▶ $\mathcal{A} \subset 2^\Omega$ a σ -field : set of “measurable” events
 - ▶ $\Omega, \phi \in \mathcal{A}$
 - ▶ $A \in \mathcal{A} \Rightarrow A^c \in \mathcal{A}$
 - ▶ $(A_n, n \in \mathbb{N}) \subset \mathcal{A} \Rightarrow \cup_{n \in \mathbb{N}} A_n \in \mathcal{A}$
- ▶ $\mathbb{P} : \mathcal{A} \rightarrow [0, 1]$ probability measure : how to choose it ?
 - ▶ $\mathbb{P}(\Omega) = 1, \mathbb{P}(\phi) = 0$
 - ▶ $(A_n, n \in \mathbb{N})$ pairwise disjoint, $\mathbb{P}(\cup_n A_n) = \sum_n \mathbb{P}(A_n)$

Continuity of measure : $A_n \uparrow A \Rightarrow \mathbb{P}(A_n) \uparrow \mathbb{P}(A)$

Random variables : A class of functions $X : \Omega \rightarrow \mathbb{R}$

2-Three interpretations of probability

- ▶ Classical (*a priori*) probability
 - ▶ Principle of indifference, equal probabilities (Laplace)
 - ▶ Criticism : problem of a loaded coin
- ▶ Subjective probability
 - ▶ Probability is a degree of belief (De Finetti, Keynes)
 - ▶ Criticism : Idealist concept, not measurable
- ▶ Frequentist probability
 - ▶ Probability is the limit of a relative frequency
 - ▶ “mass phenomena and repetitive events” –Von Mises
 - ▶ A measurable quantity !

Mathematical probability does not give a way of choosing the probability measure. It might even consider several probability measures at the same time : **In mathematical finance, real world vs. risk neutral probability.**

3-First example of conditional expectation

Consider a dice throwing experiment : $\Omega = \{1, \dots, 6\}$ **Paradigm** : σ -field = information available to an observer **Three cases** : (The notion of filtration)

- ▶ No knowledge of result : $\mathcal{F}_1 = \{\phi, \Omega\}$
- ▶ Knows if result even/odd : $\mathcal{F}_2 = \{\phi, \{1, 3, 5\}, \{2, 4, 6\}, \Omega\}$
- ▶ Full knowledge on result : $\mathcal{F}_3 = 2^\Omega$

Fair distribution of gain : $X(\omega) = \omega, \omega = 1, \dots, 6$

- ▶ $X_1(\omega) = p_1X(1) + \dots + p_6X(6)$ for all ω
- ▶ According to ω even or odd $i, j, k = 1, 3, 5$ or $2, 4, 6$

$$X_2(\omega) = [p_iX_i + p_jX_j + p_kX_k]/[p_i + p_j + p_k]$$

- ▶ $X_3(\omega) = X(\omega)$

X_1, X_2, X_3 are **conditional expectation** of X given $\mathcal{F}_1, \mathcal{F}_2, \mathcal{F}_3$

4-Random variables

Consider a function $X : \Omega \rightarrow \mathbb{R}$. X is called **measurable** if

$$\sigma(X) \subset \mathcal{A} \quad \sigma(X) = X^{-1}(\mathcal{B})$$

\mathcal{B} Borel σ -algebra. Equivalent condition

$$X^{-1}(\{t | t \leq x\}) \in \mathcal{A} \quad x \in \mathbb{R}$$

X is called a **random variable** if X is measurable **Measurability depends on \mathcal{A}** : Consider $\mathcal{F}_1 \subset \mathcal{F}_2$

- ▶ X is \mathcal{F}_1 -measurable $\Rightarrow X$ is \mathcal{F}_2 -measurable
- ▶ Equivalence does not hold
- ▶ $\mathcal{F}_1 = \mathcal{F}_2$ iff equivalence holds

Information theory : $\sigma(X_1) \subset \sigma(X_2)$ iff $H(X_1|X_2) = 0$

4-Random variables

Let $A_1, \dots, A_n \in \mathcal{A}$ and $A_i \cap A_j = \emptyset$ for $i, j = 1, \dots, n$

Simple random variable

$$X = \sum_i x_i \mathbf{1}_{A_i} \quad \sigma(X) \subset \mathcal{A}$$

Discretization

$$X_n = k2^{-n} \text{ over } \{k2^{-n} \leq X < (k+1)2^{-n}\}$$

Important result : X measurable iff X limit of simple X_n

- ▶ X_1, X_2 measurable $\Rightarrow X_1 + X_2$ measurable
- ▶ $X_1 \wedge X_2$ and $X_1 \vee X_2$ measurable
- ▶ Limit (and limit operations) of random variables is a random variable

5-Expectation

Simple random variable

$$\mathbb{E}[X] = \sum_i x_i \mathbb{P}(A_i)$$

Definition for positive X (X is said integrable)

$$\mathbb{E}[X] = \sup \mathbb{E}[Y] < \infty \quad Y \leq X \text{ simple}$$

Approximation

$$\mathbb{E}[X] = \lim_n \mathbb{E}[X_n]$$

X_1, X_2 integrable

- ▶ $\mathbb{E}[aX_1 + bX_2] = a\mathbb{E}[X_1] + b\mathbb{E}[X_2]$
- ▶ $\mathbb{P}(X < 0) = 0 \Rightarrow \mathbb{E}[X] \geq 0$
- ▶ Respects uniform convergence, but much more !

6-Distribution of a random variable

Definition of c.d.f.

$$F(x) = \mathbb{P}(X \leq x) = \lim_{t \downarrow x} F(t) \qquad \lim_{s \uparrow x} F(s) = \mathbb{P}(X < x)$$

F is càdlàg : right continuous with left limits

$$\mathbb{E}[g(X)] = \int g(x) dF(x)$$

Decomposition of F : absolutely continuous + atomic + diffuse

$$\mathbb{E}[g(X)] = \int g(x) f(x) dx \qquad F \text{ absolutely continuous}$$

Functional representation

$$\sigma(X_1) \subset \sigma(X_2) \Leftrightarrow X_1 = g(X_2) \qquad g \text{ regression function}$$

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Inverse function trick

$$X = F^{-1}(U) \qquad U \text{ uniform in } [0, 1]$$

7-Independence

$\mathcal{F}_1, \dots, \mathcal{F}_n$ are said independent if

$$\mathbb{P}(A_1 \cap \dots \cap A_n) = \mathbb{P}(A_1) \dots \mathbb{P}(A_n) \text{ for } A_1 \in \mathcal{F}_1, \dots, A_n \in \mathcal{F}_n$$

Equivalent condition (X_i is \mathcal{F}_i -measurable, $i = 1, \dots, n$)

$$\mathbb{E}[X_1 \dots X_n] = \mathbb{E}X_1 \dots \mathbb{E}X_n$$

Independence of random variables,

$$\mathbb{E}[g_1(X_1)g_2(X_2)] = \mathbb{E}[g_1(X_1)]\mathbb{E}[g_2(X_2)]$$

Equivalent condition **Kac's theorem**

$$\mathbb{E}[\exp(iu_1X_1 + iu_2X_2)] = \mathbb{E}[\exp(iu_1X_1)]\mathbb{E}[\exp(iu_2X_2)]$$

Three concepts : Independence \neq pairwise independence \neq orthogonality

I-Conditional expectation and statistics

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- ▶ Introduction and examples
- ▶ Inequalities and convergence :
 1. Chebyshev inequality
 2. Norm inequalities
 3. Convergence in probability
 4. Almost sure convergence
 5. Monotone convergence
 6. Dominated convergence
 7. Jensen's inequality

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- ▶ Conditional expectation
- ▶ Point estimation

1-Chebyshev and norm

Chebyshev inequality : Bound on tail distribution

($f(X) \geq 0$ integrable)

$$a\mathbb{P}(f(X) \geq a) \leq \mathbb{E}[f(X)] \quad a^2\mathbb{P}(|X| \geq a) \leq \mathbb{E}|X|^2$$

Norm inequalities :

$$\mathbb{E}|X_1 + X_2| \leq \mathbb{E}|X_1| + \mathbb{E}|X_2| \quad \mathbb{E}|X_1 + X_2|^2 \leq 2\mathbb{E}|X_1|^2 + 2\mathbb{E}|X_2|^2$$

General proof : Check for simple random variables

Cauchy-Schwarz : (Correlation coefficient ≤ 1)

$$\mathbb{E}[X_1 X_2]^2 \leq \mathbb{E}|X_1|^2 \mathbb{E}|X_2|^2 \quad \mathbb{E}|X_1|^2, \mathbb{E}|X_2|^2 < \infty$$

Relation between L^2 and L^1 norms

$$(\mathbb{E}|X|)^2 = (\mathbb{E}1 \cdot |X|)^2 \leq \mathbb{E}|X|^2$$

The L^2 norm is stronger

2-Convergence in probability

Definition : $X_n \xrightarrow{P} X$

$$\mathbb{P}(|X_n - X| \geq \sigma) \rightarrow 0 \text{ for } \sigma > 0$$

Relation to convergence in the mean :

$$\mathbb{E}|X_n - X| \geq \sigma \mathbb{E}(|X_n - X| \geq \sigma)$$

Relation to convergence in the square mean :

$$\mathbb{E}|X_n - X|^2 \geq \mathbb{E}|X_n - X| \geq \sigma \mathbb{E}(|X_n - X| \geq \sigma)$$

Uniformly continuous function f

$$X_n \xrightarrow{P} X \Rightarrow f(X_n) \xrightarrow{P} f(X)$$

A complete metric $d(X, Y) = \mathbb{E}[|X - Y| \wedge 1]$

3-Almost sure convergence

Definition : $X_n \rightarrow X$ a.s.

$$\mathbb{P}(\cup_N A_N) = 0 \quad A_N = \cap_{n \geq 1} \cup_{m \geq n} \{|X_m - X_m| \geq 1/N\}$$

Borel-Cantelli reasoning : $\mathbb{P}(A_N) =$

$$\lim_n \mathbb{P}(\cup_{m \geq n} \{|X_m - X_m| \geq 1/N\}) \leq \sum_{m \geq n} \mathbb{P}(|X_m - X_m| \geq 1/N)$$

Stronger than convergence in probability

$$X_n \xrightarrow{a.s.} X \Rightarrow X_n \xrightarrow{P} X$$

Counter example : Almost sure convergence is not topological

4-Monotone convergence

Statement : Even if $\mathbb{E}|X| = +\infty$, if $\mathbb{E}|X_n| < \infty$

$$X_n \uparrow X \Rightarrow \mathbb{E}X_n \uparrow \mathbb{E}X_n$$

Proof : Clear when X_n are simple !

Example :

$$\mathbb{E}[X \wedge n] \uparrow \mathbb{E}[X]$$

Example : Continuity of characteristic function

$$\mathbb{E} \left| e^{u_1 X} - e^{u_2 X} \right| \leq \mathbb{E} \left| 1 - e^{i(u_1 - u_2)X} \right| = 0$$

Note : If $X_n \xrightarrow{P} X$ and increasing then $X_n \uparrow X$ a.s.

5-Dominated convergence

Statement : $|X_n| \leq Y, \mathbb{E}|Y| < \infty$

$$X_n \rightarrow X \Rightarrow \lim_n \mathbb{E}X_n = \mathbb{E}X$$

Y controls large values of X_n

$$\mathbb{E}[X_n \mathbf{1}_A] \leq \mathbb{E}[Y \mathbf{1}_A] \quad A \in \mathcal{A}$$

Egorov's theorem : For $\delta > 0$ there exists $A_\delta \in \mathcal{A}$, $\mathbb{P}(A_\delta^c) < \delta$ and X_n converge uniformly on A_δ .

Proof : Uniform convergence is applied locally

$$\mathbb{E}[X_n - X] \leq \mathbb{E}[X_n - X; A_\delta] + \mathbb{E}[X_n - X; A_\delta^c]$$

Extension : Uniform integrability

6-Jensen's inequality

Statement : Convex function f

$$f(\mathbb{E}[X]) \leq \mathbb{E}[f(X)]$$

Example : $f(x) = |x|^p, p \geq 1$

Example : $f(x) = -\log(x)$ appears in information theory

Proof : Clear when X is simple

$$f(\mathbb{E}[X]) = f\left(\sum x_i \mathbb{P}(A_i)\right) \leq \sum \mathbb{P}(A_i) f(x_i)$$

To go on, use continuity of f and dominated convergence. **Other**

proof : f is defined at $\mathbb{E}[X]$, by convexity

$$f(X) \geq f(\mathbb{E}[X]) + K(X - \mathbb{E}[X]) \quad K \in \mathbb{R}$$